

TECHNICAL CHARACTERISTICS* OF THE MOBILE SYSTEM FOR COUNTERING SMALL-SIZED UAVS

| No. | Denomination | Value |
|-----|--|--|
| 1 | Operating frequency range of continuous radio surveillance | from 0.4 to 6 GHz |
| 2 | Surveillance links | radio surveillance Wi-Fi DJI LTE (4G) |
| 3 | Coverage sector of surveillance links | 360° |
| 4 | RMS error of direction finding in azimuth, no more than | 3° |
| 5 | Number of independent controlled signal generation links in 40° sector (with circular rotation) in the frequency ranges: | |
| | from 0.4 to 3 GHz | 1 |
| | from 0.4 to 6 GHz | 2 |
| 6 | Number of fixed frequency ranges for generating group jamming signals in 360° sector, not less than | 10 |
| 7 | Maximum bandwidth of the generated signal in the frequency ranges: | |
| | from 0.4 to 0.85 GHz | 100 MHz |
| | from 0.85 to 3 GHz | 300 MHz |
| | from 3 to 6 GHz | 300 MHz |
| 8 | Operating temperature range for equipment | from – 30 °C up to + 50 °C |
| 9 | Power supply voltage | 220 V ± 10% 50 Hz |
| 10 | Maximum power consumption of AC mains, no more than | 5500 VA |
| 11 | Equipment weight (without transport base), no more than | 850 kg |
| 12 | UAV signal detection and identification range:** | |
| | UAV of quadcopter-type with power budget of emitting signal no less than 0.2 W | up to 7 km |
| | UAV of aircraft-type with power budget of emitting signal no less than 1 W | up to 25 km |
| 13 | Control link jamming range:** | |
| | UAV with power budget of emitting signal no less than 0.2 W | up to 4 km |
| | UAV with power budget of emitting signal no less than 1 W | up to 20 km |
| 14 | Satellite navigation link jamming range (circular mode 360°), no less than | 4 km |
| 15 | Satellite navigation link jamming range (sector mode 40°) with the ability to rotate 360°, no less than | 20 km |
| 16 | System deployment/tear-down time from transporting to working position, no more than | 5 minutes |
| 17 | Crew | operator – 1 driver-technician – 1 |

* Technical characteristics of the System may change as continuous modernization of the System and the UAVs opposing to it is carried out;

** Specific detection and jamming ranges of UAV control links depend on:

- the distances between the control panel, the UAV and the System;
- the type of UAV control signals;
- the transmitter power of the UAV control panel,

and also depend on:

- angles of closure of the visible radio horizon;
- electromagnetic environment (presence and distance to mobile communication base stations and Wi-Fi modems);
- elevation changes in terrain;
- height and topology of surrounding buildings;
- presence of unintentional noise sources.